

## Problem 9.1

$$\begin{aligned} \text{A) } & \delta(t-3) * [\delta(t) + 2e^{-t} \cos(5\pi t) u(t)] \\ &= \delta(t-3) * \delta(t) + \delta(t-3) * 2e^{-t} \cos(5\pi t) u(t) \\ &= \delta(t-3) + 2e^{-(t-3)} \cos(5\pi(t-3)) u(t-3) \\ &= \delta(t-3) + 2e^{-(t-3)} \cos(5\pi t - \pi) u(t-3) \end{aligned}$$

for the phase:  
 $-15\pi = -\pi$

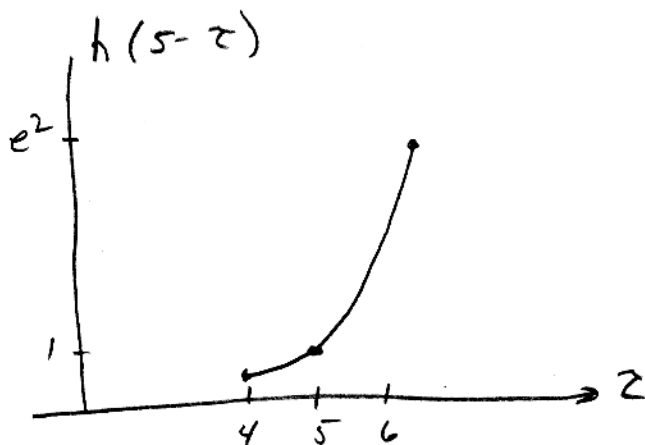
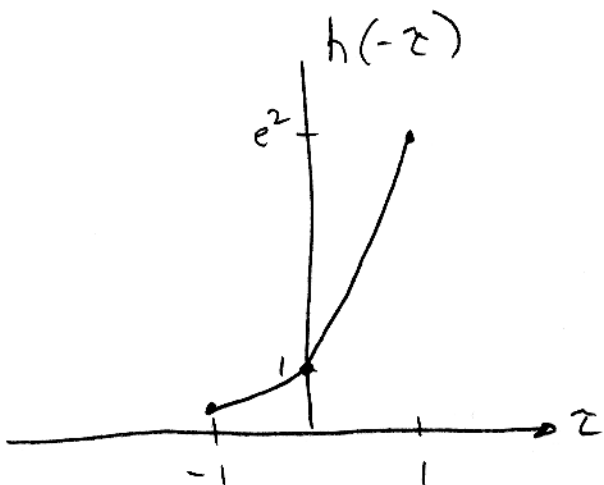
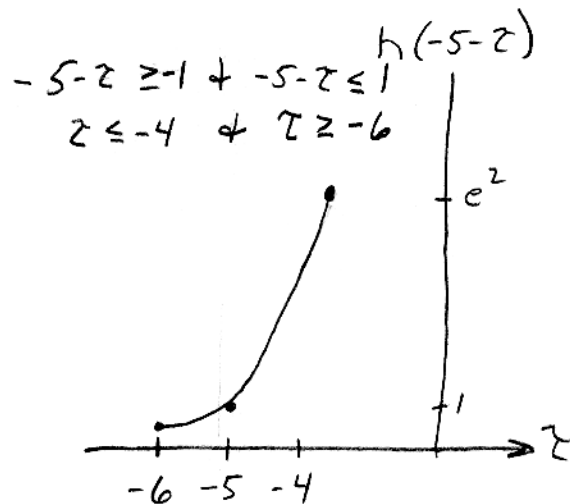
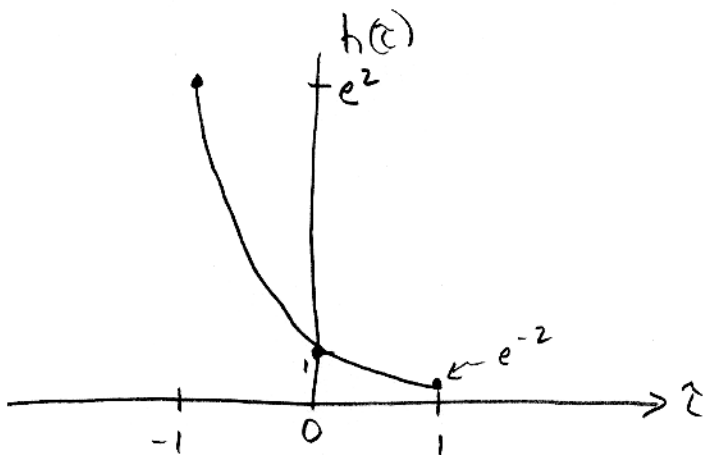
$$\begin{aligned} \text{B) } & [u(-t+3) - u(t)] [\delta(t-1) + \delta(t-4)] \\ &= u(-t+3) \delta(t-1) + u(t+3) \delta(t-4) - u(t) \delta(t-1) - u(t) \delta(t-4) \\ &= u(2) \delta(t-1) + u(-1) \delta(t-4) - u(1) \delta(t-1) - u(4) \delta(t-4) \\ &= \delta(t-1) - \delta(t-1) - \delta(t-4) \\ &= -\delta(t-4) \end{aligned}$$

$$\begin{aligned} \text{C) } & \frac{d}{dt} [\cos(5\pi t) u(t-1)] = \cos(5\pi t) \left[ \frac{d u(t-1)}{dt} \right] + \left[ \frac{d}{dt} (\cos(5\pi t)) \right] u(t-1) \\ &= (\cos(5\pi t)) \delta(t-1) - 5\pi (\sin(5\pi t)) u(t-1) \\ &= \cos(5\pi) \delta(t-1) - 5\pi (\sin(5\pi t)) u(t-1) \\ &= -\delta(t-1) - 5\pi (\sin(5\pi t)) u(t-1) \end{aligned}$$

$$\begin{aligned} \text{D) } & \int_{-\infty}^t e^{-(z-1)} \delta(z-1) dz \quad \text{using } u(t) = \int_{-\infty}^t \delta(z) dz \\ &= \int_{-\infty}^t e^{-(1-1)} \delta(z-1) dz = \int_{-\infty}^t \delta(z-1) dz \\ &= u(t-1) \end{aligned}$$

## Problem 9.2

A) Plot  $h(z)$  and  $h(t-z)$  for  $t = -5, 0, 5$



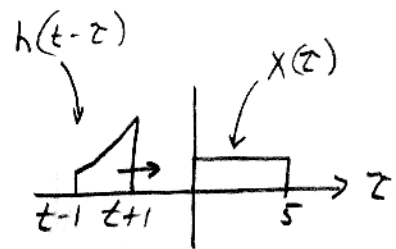
B) The system is not causal.  $h(t) \neq 0$  for  $t < 0$ .

$$C) y(t) = x(t) * h(t) = \delta(t+5) * e^{-2t} = e^{-2(t+5)} \text{ for } -6 \leq t \leq -4$$
$$\Rightarrow y(t) = \begin{cases} e^{-10} e^{-2t} & -6 \leq t \leq -4 \\ 0 & \text{otherwise} \end{cases}$$

# Problem 9.2 (continued)

$$D) \quad X(t) = \begin{cases} 1 & 0 \leq t \leq 5 \\ 0 & \text{otherwise} \end{cases}$$

$$y(t) = \int_{-\infty}^{\infty} X(z)h(t-z)dz = X(t) * h(t) =$$



Interval 1 For  $t+1 < 0$   
 $t < -1$ , functions don't overlap

$$y(t) = 0 \quad t < -1$$

Interval 2  $t+1 \geq 0$  &  $t-1 < 0 \Rightarrow -1 \leq t \leq 1$

$$y(t) = \int_0^{t+1} 1 e^{-2(t-z)} dz = e^{-2t} \int_0^{t+1} e^{2z} dz$$

$$= e^{-2t} \left( \frac{e^{2(t+1)}}{2} - \frac{1}{2} \right)$$

$$y(t) = \frac{e^2}{2} - \frac{e^{-2t}}{2}$$

Interval 3  $t+1 \leq 5$  &  $t-1 \geq 0 \Rightarrow 1 \leq t \leq 4$

$$y(t) = \int_{t-1}^{t+1} 1 e^{-2(t-z)} dz = e^{-2t} \int_{t-1}^{t+1} e^{2z} dz = e^{-2t} \left( \frac{e^{2(t+1)}}{2} - \frac{e^{2(t-1)}}{2} \right)$$

$$y(t) = \frac{e^2}{2} - \frac{e^{-2}}{2}$$

Interval 4  $t+1 \geq 5$  &  $t-1 < 5 \Rightarrow 4 \leq t \leq 6$

$$y(t) = \int_{t-1}^5 1 e^{-2(t-z)} dz = \frac{e^{-2(t-5)}}{2} - \frac{e^{-2}}{2}$$

Interval 5  $t-1 \geq 5 \Rightarrow t \geq 6$

$$y(t) = 0, \text{ functions don't overlap}$$

## Problem 9.3

A) If  $y(t) = \int_{-\infty}^{t+4} x(\tau) d\tau$ , then  $h(t) = \int_{-\infty}^{t+4} \delta(\tau) d\tau$

$$\Rightarrow h(t) = u(t+4)$$

B) A system is stable if:

1. a bounded input produces bounded outputs

2.  $\int_{-\infty}^{\infty} |h(t)| dt < \infty$

Using criteria 2,  $\int_{-\infty}^{\infty} u(t+4) dt = \int_{-\infty}^{\infty} dt = \infty$

Therefore, the system is unstable.

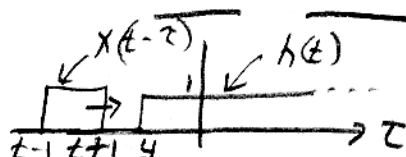
C) A system is causal if:

1.  $y(t_0)$  depends only on  $x(\tau)$  for  $\tau \leq t_0$

2.  $h(t) = 0$  for  $t < 0$

Using criteria 2,  $h(t) = u(t+4) \neq 0$  for all  $t < 0$

Therefore, the system is not causal.

D)  $y(t) = x(t) * h(t) =$  

Interval 1

$$t+1 \leq -4 \Rightarrow t \leq -5$$

$$y(t) = 0$$

Interval 2

$$t+1 \geq -4 \text{ and } t-1 \leq -4 \Rightarrow -5 \leq t \leq -3$$

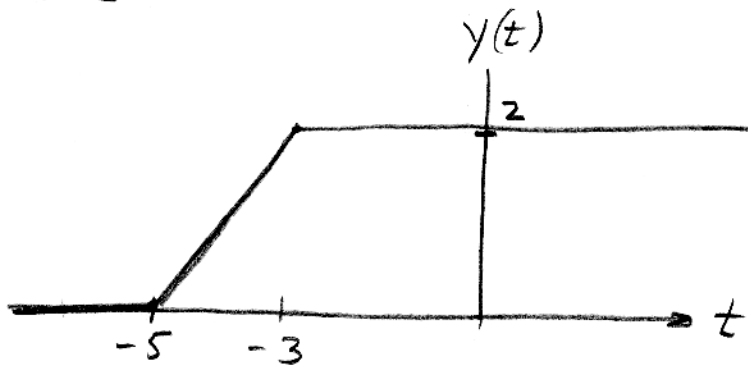
$$y(t) = \int_{-4}^{t+1} d\tau = t+5$$

## Problem 9.3 (continued)

Interval 3  $t-1 \geq -4 \Rightarrow t \geq -3$

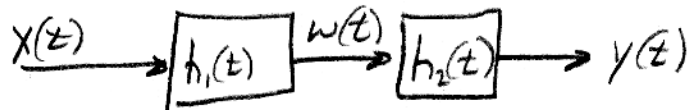
$$y(t) = \int_{t-1}^{t+1} dz = 2$$

Plot of  $y(t)$



E) If  $x(t) = u(t)$  produced  $y(t) = (t+4)u(t+4)$ ,  
then by time invariance  $x_1(t) = u(t+1)$  produces  
 $y_1(t) = (t+5)u(t+5)$  and  $x_2(t) = u(t-1)$  produces  
 $y_2(t) = (t+3)u(t+3)$ . Using linearity (superposition),  
if  $x(t) = x_1(t) - x_2(t)$ , then  $y(t) = y_1(t) - y_2(t)$ .  
Therefore  $y(t) = (t+5)u(t+5) - (t+3)u(t+3)$

# Problem 9.4



A) If  $w(t) = \int_{-\infty}^t x(\tau) d\tau$ , then  $h_1(t) = \int_{-\infty}^t \delta(\tau) d\tau = u(t)$

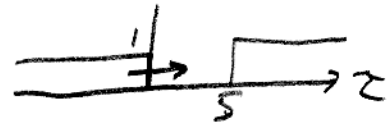
Therefore  $h_{\text{overall system}}(t) = h_1(t) * h_2(t) = u(t) * u(t-5)$

Interval 1  $t < 5$

$$h(t) = y(t) = 0$$

Interval 2  $t \geq 5$

$$h(t) = y(t) = \int_5^t d\tau = t - 5$$



B) If  $w(t) = \frac{d}{dt} x(t) + 3x(t)$  and  $h_{\text{overall system}}(t) = \delta(t)$

$$\begin{aligned} h_{\text{overall system}}(t) &= \left( \frac{d}{dt} \delta(t) + 3\delta(t) \right) * h_2(t) \\ &= \left( \frac{d}{dt} \delta(t) + 3\delta(t) \right) * e^{\alpha t} u(t) = \frac{d}{dt} \left( e^{\alpha t} u(t) \right) + 3e^{\alpha t} u(t) \\ &= \alpha e^{\alpha t} u(t) + e^{\alpha t} \delta(t) + 3e^{\alpha t} u(t) \\ &= (3 + \alpha) e^{\alpha t} u(t) + \delta(t) \end{aligned}$$

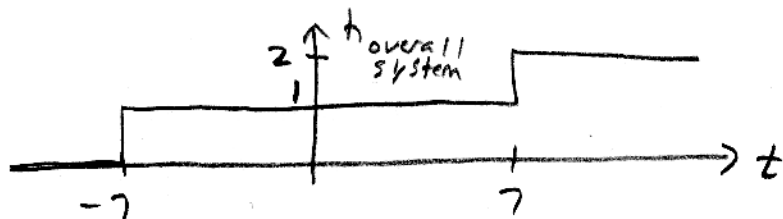
Therefore for  $h_{\text{overall system}}(t) = \delta(t)$ , then  $\alpha = -3$

$$h_2(t) = e^{-3t} u(t)$$

## Problem 9.5

A)  $h_1(t) = \delta(t+7)$ ,  $h_2(t) = \delta(t-7)$ ,  $h_3(t) = u(t)$

$$\begin{aligned} h_{\text{overall system}}(t) &= (h_1(t) + h_2(t)) * h_3(t) \\ &= (\delta(t+7) + \delta(t-7)) * u(t) \\ &= \delta(t+7) * u(t) + \delta(t-7) * u(t) \\ &= u(t+7) + u(t-7) \end{aligned}$$



B) Causal if  $h(t) = 0$  for  $t < 0$ . From graph above,  $h(t) \neq 0$  for  $t < 0$ . Therefore, the system is not causal.

C) Stable if  $\int_{-\infty}^{\infty} |h(t)| dt < \infty$

$$\text{For this system } \int_{-\infty}^{\infty} |h(t)| dt = \int_{-\infty}^{-7} dt + \int_{-7}^{\infty} 2 dt = \infty$$

Therefore the system is not stable.