

SOLUTIONS to Final Exam

Problem 1 (20%)

Let X and Y be two independent standardized (zero mean, unit variance) Gaussian random variables. Define another two additional random variables $U=aX+bY$, and $V=aX-bY$, with a and b being two positive scaling constants.

- (a) Find the means and variances of U and V ;
- (b) Find the correlation $E[UV]$ and correlation coefficient of U and V .
- (c) Use the Jacobian transformation to find the joint probability density function of U and V , expressing it in the bivariate Gaussian density form [Recall that the Jacobian matrix J is defined as a 2×2 matrix with $\partial x / \partial u$, $\partial x / \partial v$, $\partial y / \partial u$, $\partial y / \partial v$ as its elements];
- (d) Make sure your answers in Parts (a) and (b) agree with the pdf in Part (c);
- (e) Find the marginal probability density functions, $f_U(u)$ and $f_V(v)$. Are the marginal densities depending on the value of the correlation coefficient?
- (f) Under what conditions can U and V be independent? State your reasons.

Solution:

(a) $E[U] = E[aX] + E[bY] = 0$ and $E[V] = E[aX] - E[bY] = 0$,

$$\sigma_U^2 = \text{Var}[aX] + \text{Var}[bY] = a^2 + b^2, \quad \sigma_V^2 = \text{Var}[aX] + \text{Var}[bY] = a^2 + b^2;$$

(b) $E[UV] = E[a^2 X^2 - b^2 Y^2] = a^2 - b^2$, $\rho = E[UV] / [\sigma_U \sigma_V] = (a^2 - b^2) / (a^2 + b^2)$;

(c) First perform the mapping, we have $x = \frac{1}{2a}(u+v)$ and $y = \frac{1}{2b}(u-v)$, so we have

$$\partial x / \partial u = \frac{1}{2a}, \partial x / \partial v = \frac{1}{2a}, \partial y / \partial u = \frac{1}{2b}, \partial y / \partial v = -\frac{1}{2b}, \text{ and } |\det(J)| = |-\frac{1}{2ab}| = \frac{1}{2ab}$$

the joint pdf $f(x, y) = \frac{1}{2\pi} \exp[-\frac{1}{2}(x^2 + y^2)] = f_X(x) * f_Y(y)$, so we have

$$g(u, v) = |J| f(\Psi_1(u, v), \Psi_2(u, v)) = \frac{1}{2ab * 2\pi} \exp[-\frac{1}{2} \{ \frac{(u+v)^2}{4a^2} + \frac{(u-v)^2}{4b^2} \}]$$

$$= \frac{1}{2ab * 2\pi} \exp[-\frac{1}{2} \{ (\frac{1}{4a^2} + \frac{1}{4b^2})(u^2 + v^2) - (-\frac{1}{4a^2} + \frac{1}{4b^2})2uv \}]$$

$$= \frac{1}{\sqrt{(2\pi)^2 * (1 - \rho^2) \sigma_U^2 \sigma_V^2}} \exp[-\frac{1}{2(1 - \rho^2)} \{ \frac{u^2}{\sigma_U^2} + \frac{v^2}{\sigma_V^2} - \frac{2\rho uv}{\sigma_U \sigma_V} \}]$$

$$\Rightarrow \rho = \frac{(-1/4a^2 + 1/4b^2)}{(1/4a^2 + 1/4b^2)} = \frac{(a^2 - b^2)}{(a^2 + b^2)} \text{ (from the above bivariate Gaussian pdf);}$$

(d) The answers in Parts (a) and (b) agree with the parameters in the pdf in Part (c);

(e) Since $1 - \rho^2 = 4a^2b^2 / (a^2 + b^2)^2$, and $\sigma_U^2 = \sigma_V^2 = \sigma_U \sigma_V = a^2 + b^2$, we have the exponent in $g(u, v)$ can be simplified to form a perfect square, i.e.

$$\frac{1}{2(1 - \rho^2)} \left(\frac{u^2}{\sigma_U^2} + \frac{v^2}{\sigma_V^2} - \frac{2\rho uv}{\sigma_U \sigma_V} \right) = \frac{(a^2 + b^2)}{2 * (4a^2b^2)} * [(u - \rho v)^2] + \frac{1}{2 * (a^2 + b^2)} v^2$$

$$f_V(v) = \int_{-\infty}^{\infty} g(u, v) du = \frac{1}{\sqrt{2\pi\sigma_U^2|W|}} \int_{-\infty}^{\infty} \exp[-\frac{(u - \rho v)^2}{2\sigma_U^2|W|}] du * \frac{1}{\sqrt{2\pi\sigma_V^2}} \exp[-\frac{v^2}{2\sigma_V^2}]$$

$$\Rightarrow f_V(v) = \frac{1}{\sqrt{2\pi\sigma_V^2}} \exp[-\frac{v^2}{2\sigma_V^2}] \text{ [Note: } \sigma_{U|V}^2 = \frac{4a^2b^2}{(a^2 + b^2)} = (1 - \rho^2)\sigma_U^2 \text{].}$$

$$\text{Similarly } f_U(u) = \frac{1}{\sqrt{2\pi\sigma_U^2}} \exp[-\frac{u^2}{2\sigma_U^2}] \Rightarrow f_U(u) \text{ and } f_V(v) \text{ do not depend on } \rho;$$

(f) U and V are independent Gaussian r. v.'s if $E[UV] = 0$, or $a = b$;

Problem 2 (20%)

A passenger can take two different bus lines to work. Both lines stop at the same bus stop. Let X and Y be independent random variables representing the times of arrival for the bus of line 1 and line 2, respectively. It is known that X and Y have exponential densities with means of 5 and 10 minutes, respectively. Let Z be the random variable representing time the passenger will wait for a bus, i.e. $Z = \min(X, Y)$. [Hint: $f_X(x) = K_x e^{-a_x x} u(x)$, and $f_Y(y) = K_y e^{-a_y y} u(y)$, with $u(\cdot)$ a step function]

- (a) Find the pairs of values of (K_x, a_x) and (K_y, a_y) to make $f_X(x)$ and $f_Y(y)$ valid densities, and with the corresponding means of 5 and 10 minutes ;
- (b) Find $P(Z > 5)$, the probability that after 5 minutes no bus has arrived yet. Interpret your result and make sure the answer is reasonable [Hint: divide the (x, y) plane into two regions : $R_1 = \{Y \geq X\}$ and $R_2 = \{X > Y\}$];
- (c) Find the probability density function of Z [Hint: it is obtained by taking the derivative of the corresponding distribution function, $F_Z(z) = P(Z \leq z)$];
- (d) What is the average time, $E[Z]$, the passenger will wait at the bus stop?
- (e) Compare $E[Z]$ with $E[X]$ and $E[Y]$, and make sure your answer in Part (d) is intuitively reasonable. Check this answer with the result in Part (b).

Solution:

(a) $\int_0^\infty K_x e^{-a_x x} dx = -\frac{K_x}{a_x} e^{-a_x x} \Big|_0^\infty = \frac{K_x}{a_x} = 1 \Rightarrow K_x = a_x$, since $E[X] = 5$,

we have $E[X] = \int_0^\infty a_x x e^{-a_x x} dx = (-a_x x e^{-a_x x} - \frac{1}{a_x} e^{-a_x x}) \Big|_0^\infty = \frac{1}{a_x} \Rightarrow a_x = \frac{1}{5}, K_x = \frac{1}{5}$;

similarly since $E[Y] = 10 \Rightarrow a_y = \frac{1}{10}, K_y = \frac{1}{10}$;

- (b) Partition the (x, y) plane into two regions, $R_1 = \{Y \geq X\} (Z = X)$ and $R_2 = \{Y < X\} (Z = Y)$

For any given $z \geq 0$, $P(Z > z) = P(X > z, R_1) + P(Y > z, R_2)$

$$\begin{aligned} &= \int_z^\infty \left[\int_x^\infty f_Y(y) dy \right] f_X(x) dx + \int_z^\infty \left[\int_y^\infty f_X(x) dx \right] f_Y(y) dy \\ &= \int_z^\infty [(-e^{-y/10}) \Big|_x^\infty] \frac{1}{5} e^{-x/5} dx + \int_z^\infty [(-e^{-x/5}) \Big|_y^\infty] \frac{1}{10} e^{-y/10} dy \\ &= e^{-\frac{3}{10}z}, \text{ for } z = 5, P(Z > 5) = e^{-\frac{3}{2}} = 0.2231; \end{aligned}$$

(c) Since $F_Z(z) = P(Z \leq z) = 1 - P(Z > z) \Rightarrow f_Z(z) = dF_Z(z) / dz = \frac{3}{10} e^{-\frac{3}{10}z}$;

- (d) $E[Z] = 10/3$, the expected waiting time;

- (e) Clearly $E[Z]$ is expected to be less than either $E[X] = 5$ or $E[Y] = 10$,

because the passenger always takes the minimum waiting time with $Z = \min(X, Y)$.

Problem 3 (20%)

You play with a friend the following game: you flip a coin provided by your friend and if the result is Head you win \$1 while if it is a Tail you lost \$1 (i.e. you

win -\$1). Let X_i be the random variable describing the amount you win at the i -th coin flip. You play the game $n=2,500$ times. Let V be the number of winning games, and $S = \sum_{i=1}^n X_i$ be the random variable representing the total winning amount after these plays. First assume a fair coin is used, i.e. $p=P(X=1) = P(X=-1)=0.5$.

(a) V is known to have a Binomial distribution with $P_n(V = v) = {}_n C_v p^v (1-p)^{n-v}$,

where ${}_n C_v = \frac{n!}{v!(n-v)!}$, show that $E[V]=np$, and $\text{Var}[V]=np(1-p)$;

(b) According to the Law of Large Number, V is approximately normal when n is large, find the approximate probability density functions of V and S ;

(c) What is the probability that at the end of the game you lost more than \$300, i.e. find $P(S < -300)$ [Hint: an approximation is fine, no need to be exact];

(d) At the end of the game you lost \$300. You suspect your friend cheated and the coin is biased. Estimate the value of the success rate, $p=P(X=1)$;

(e) Construct a 99% confidence interval for the unknown parameter, p ;

(f) Do you think the coin is fair? Why?

Solution:

(a) $P_n(V = v) = {}_n C_v p^v (1-p)^{n-v}$

$$\begin{aligned} E[V] &= \sum_{v=0}^n \frac{n!}{v!(n-v)!} v p^v (1-p)^{n-v} \\ &= np * \sum_{v=1}^n \frac{(n-1)!}{(v-1)!(n-v)!} p^{v-1} (1-p)^{n-v} \\ &= np * \sum_{l=0}^{n-1} \frac{l!}{l!(n-l)!} p^l (1-p)^{n-l} = np \end{aligned}$$

[with a change of variable of $m = n - 1$ and $l = v - 1$]

$$\begin{aligned} E[V^2 - V] &= \sum_{v=0}^n \frac{n!}{v!(n-v)!} (v^2 - v) p^v (1-p)^{n-v} \\ &= n(n-1)p^2 * \sum_{v=2}^n \frac{(n-2)!}{(v-2)!(n-v)!} p^{v-2} (1-p)^{n-v} \\ &= n(n-1)p^2 * \sum_{l=0}^{n-2} \frac{l!}{l!(n-l)!} p^l (1-p)^{n-l} = n(n-1)p^2 \end{aligned}$$

$$\Rightarrow \text{Var}[V] = E[V^2 - V] + E[V] - (E[V])^2 = n(n-1)p^2 + np - n^2 p^2 = np(1-p);$$

(b) $S = V - (n - V) = 2V - n$, a linear function of a Gaussian V , when n is large.

$$\mu_s = E(S) = 2np - n = n(2p - 1), \sigma_s^2 = \text{Var}[S] = 4\text{Var}[V] = 4np(1-p)$$

Since V is $N(np, np(1-p))$, S is $N(n(2p-1), 4np(1-p))$;

(c) If we assume $p = 0.5$, then $f_s(s) = \frac{1}{\sqrt{2\pi} * 50} \exp[-\frac{s^2}{5000}]$, so

$$P(S < -300) = \frac{1}{\sqrt{2\pi} * 50} \int_{-\infty}^{-300} f_s(s) ds = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{-6} e^{-x^2/2} dx \approx 0$$

- (d) Using the result in Part (c), the probability that you lost \$300 at the end of the game is almost zero, so it is highly likely that $p \neq 0.5$, i.e. the coin is biased.
 An unbiased estimate for p is $\hat{p} = v/n$, with $v = (s+n)/2 = 1100$, or $\hat{p} = 0.44$;
- (e) Using the result in Part(c), V/n is $N(p, p(1-p)/n)$. So a 99% confidence interval can be established as $[\hat{p} - k\hat{\sigma}_p, \hat{p} + k\hat{\sigma}_p]$, such that $k = 2.575$, and $\hat{\sigma}_p \approx \sqrt{\hat{p}(1-\hat{p})/n} \approx 0.01 \Rightarrow$ an estimate of the 99% confidence interval is $[0.4143, 0.4658] \Rightarrow$ the value of $p = 0.5$ does not fall in the above interval;
- (f) Base on the results in Parts (c), (d) and (e), we can conclude that the coin is not fair.

Problem 4 (20%)

It is desirable to estimate the difference between the mean sale prices for all residential properties sold during 1983 in two neighborhoods D and E of a mid-sized Florida city. A random set of n_D sale prices for neighborhood D was collected with X_{Di} being the i -th sample with unknown mean μ_D and variance σ_D^2 . Another random set of n_E sale prices for neighborhood E was also collected with X_{Ej} being the j -th sample with unknown mean μ_E and variance σ_E^2 . All the random samples are assumed to be mutually independent of each other. We are interested in estimating the mean difference $\mu_Y = \mu_D - \mu_E$.

- (a) Define a new random variable Y , which serve as a good estimate for μ_Y , if corresponding random samples are used to form a sample statistic for Y ;
- (b) Find the mean and standard deviation σ_Y of Y , is Y an unbiased estimate?
- (c) Give a sample statistic which serve as an unbiased point estimates for σ_Y^2 ;
- (d) From the actual samples in surveys we have obtained the following set of measurements: $n_D = 30$ (sample size), $n_E = 40$ (sample size), $\bar{x}_D = \$52,356$ (sample mean), (sample mean), $\tilde{s}_{D2} = \$10,572$ (sample standard deviation), $\bar{x}_E = \$66,491$ (sample mean), and $\tilde{s}_{E2} = \$14,264$ (sample standard deviation). Construct a 95% confidence interval for μ_Y [Hint: Find the approximate large sample density for the corresponding sample statistic];
- (e) If we want to test a null hypothesis, $H_0: \mu_Y = 0$ against an alternative hypothesis, $H_1: \mu_Y < 0$, construct a statistical test. Based on the data in part(c), decide if we should reject H_0 at a 95% confidence level, why?

Solution:

- (a) Let $Y = \hat{X}_D - \hat{X}_E =$ sample mean difference between the two communities

$$\text{with } \hat{X}_D = \frac{1}{n_D} \sum_{i=1}^{n_D} X_{Di} \text{ and } \hat{X}_E = \frac{1}{n_E} \sum_{j=1}^{n_E} X_{Ej} \text{ where } x_{Di} \text{ and } x_{Ej} \text{ are samples.}$$

- (b) $E[Y] = E[\hat{X}_D] - E[\hat{X}_E] = \mu_D - \mu_E \Rightarrow Y$ is an unbiased estimate of the mean difference,

$$\text{and next we show in the following that } \sigma_Y = \sqrt{\frac{\sigma_D^2}{n_D} + \frac{\sigma_E^2}{n_E}} \text{ (intuitively sound).}$$

$$\begin{aligned}
\text{Var}[Y] &= E[Y^2] - (E[Y])^2 = \frac{1}{n_D^2} \left(\sum_{i=1}^{n_D} E[X_{D_i}^2] \right) + \sum_{i=1}^{n_D} \sum_{l \neq i}^{n_D} E[X_{D_i}]E[X_{D_l}] \\
&+ \frac{1}{n_E^2} \left(\sum_{j=1}^{n_E} E[X_{E_j}^2] \right) + \sum_{j=1}^{n_E} \sum_{k \neq j}^{n_E} E[X_{E_j}]E[X_{E_k}] - \frac{2}{n_D n_E} \sum_{i=1}^{n_D} \sum_{j=1}^{n_E} E[X_{D_i}]E[X_{E_j}] - (\mu_D - \mu_E)^2 \\
&= \frac{1}{n_D^2} [n_D \sigma_D^2 + n_D^2 \mu_D^2] + \frac{1}{n_E^2} [n_E \sigma_E^2 + n_E^2 \mu_E^2] - \frac{2}{n_D n_E} [(n_D \mu_D)(n_E \mu_E)] - (\mu_D - \mu_E)^2 \\
&= \frac{\sigma_D^2}{n_D} + \frac{\sigma_E^2}{n_E} \quad (\text{sum of the two variances of the corresponding individual sample means});
\end{aligned}$$

(c) Let $\tilde{S}_D^2 = \frac{1}{(n_D - 1)} \sum_{i=1}^{n_D} E[(X_{D_i} - \hat{X}_D)^2]$ and $\tilde{S}_E^2 = \frac{1}{(n_E - 1)} \sum_{j=1}^{n_E} E[(X_{E_j} - \hat{X}_E)^2]$, then

$$E[\tilde{S}_D^2] = \sigma_D^2 \quad \text{and} \quad E[\tilde{S}_E^2] = \sigma_E^2 \Rightarrow \tilde{S}_D^2 \quad \text{and} \quad \tilde{S}_E^2 \quad \text{are unbiased estimates.}$$

If we defined $S_Y^2 = \frac{\tilde{S}_D^2}{n_D} + \frac{\tilde{S}_E^2}{n_E}$, then S_Y^2 is an unbiased estimate of σ_Y^2 .

By replacing the above random variables with respective sample statistics,

$$\text{we have a } S_Y^2 \text{-statistic} = \frac{1}{n_D(n_D - 1)} \sum_{i=1}^{n_D} E[(x_{D_i} - \bar{x}_D)^2] + \frac{1}{n_E(n_E - 1)} \sum_{j=1}^{n_E} E[(x_{E_j} - \bar{x}_E)^2];$$

(d) If we have large sample statistics, i.e. n_D and n_E are large enough (e.g. ≥ 30)

then Y is the difference of two Gaussian random variables, so Y is $N(\mu_Y, \sigma_Y^2)$.

An estimate of the 95% confidence is $[\bar{x}_D - \bar{x}_E - 1.96s_Y, \bar{x}_D - \bar{x}_E + 1.96s_Y]$, $s_Y = 3095$,

or $[-\$20,201, -\$8,069]$, by plugging in the sample values from the given measurements;

(e) We can construct a one-sided test, by using the approximate Gaussian z -statistic,

$$z = \frac{(\bar{x}_D - \bar{x}_E) - \hat{\mu}_Y}{s_Y} = \frac{-14135}{3095} = -4.567 \ll -1.645 \quad (\hat{\mu}_Y = 0, s_Y = 3,095, z_{0.05} = \pm 1.645).$$

Therefore we can reject the hypothesis $H_0 : \mu_Y = 0$ at a 95% confidence level.

Problem 5 (20%)

A zero-mean random process $X(t)$ is wide-sense stationary, with autocorrelation function $R_X(\tau) = 10e^{-2|\tau|} - 5e^{-4|\tau|}$. Another zero-mean, stationary noise process, $N(t)$, has a band-pass spectral density: $S_N(\omega) = 1/5$, for $10\pi \leq \omega \leq 20\pi$, and $S_N(\omega) = 0$ elsewhere. Assume $X(t)$ and $N(t)$ are independent. Define a noisy process: $Y(t) = aX(t-q) + N(t)$, where a is a constant much smaller than 1, q represents a round-trip time delay in return signal acquisition to measure the distance to a target using the signal, $X(t)$.

- Find the spectral density, $S_X(\omega)$, and $S_X(s)$ (with $s \triangleq j\omega$) of process $X(t)$;
- Is $S_X(\omega)$ a rational spectrum? If so, find all the poles and zeroes of $S_X(s)$?
- Find $\int_{-\infty}^{\infty} S_X(\omega) d\omega$, and verify $\int_{-\infty}^{\infty} S_X(\omega) d\omega = R_X(0) = E[X^2]$ [Hint: the integration can be accomplished by the Residue Theorem];
- Find the mean-square value of the noise process, $N(t)$;
- Find the autocorrelation, $R_Y(\tau)$, and mean-square value, $R_Y(0)$, of $Y(t)$;

- (f) Compute the cross-correlation function, $R_{XY}(\tau) = E[X(t)Y(t+\tau)]$, and the cross-spectral density, $S_{XY}(\omega) = \int_{-\infty}^{\infty} R_{XY}(\tau)e^{-j\omega\tau} d\tau$;
- (g) Describe a way to estimate the delay, q .

Solution:

$$\begin{aligned} \text{(a)} \quad S_X(\omega) &= \int_{-\infty}^{\infty} R_X(\tau)e^{-j\omega\tau} d\tau = \int_{-\infty}^0 10e^{(2-j\omega)\tau} d\tau + \int_0^{\infty} 10e^{-(2+j\omega)\tau} d\tau - \int_{-\infty}^0 5e^{(4-j\omega)\tau} d\tau - \int_0^{\infty} 5e^{-(4+j\omega)\tau} d\tau \\ &= \frac{10e^{(2-j\omega)\tau}}{2-j\omega} \Big|_{-\infty}^0 + \frac{-10e^{-(2+j\omega)\tau}}{2+j\omega} \Big|_0^{\infty} - \frac{5e^{(4-j\omega)\tau}}{4-j\omega} \Big|_{-\infty}^0 - \frac{-5e^{-(4+j\omega)\tau}}{4+j\omega} \Big|_0^{\infty} \\ &= \frac{40}{4+\omega^2} - \frac{40}{16+\omega^2} = \frac{480}{(4+\omega^2)(16+\omega^2)} \Rightarrow S_X(s) = \frac{480}{(4-s^2)(16-s^2)}; \end{aligned}$$

(b) Clearly, $S_X(\omega)$ is a rational spectrum, and $S_X(s)$ has poles at $\pm 2, \pm 4$;

$$\begin{aligned} \text{(c)} \quad E[X^2] &= \frac{1}{2\pi} \int_{-\infty}^{\infty} S_X(\omega) d\omega = \text{residue}_{s=-2} + \text{residue}_{s=-4} \\ &= \frac{480}{-(2-s)(16-s^2)} \Big|_{s=-2} + \frac{480}{-(4-s)(4-s^2)} \Big|_{s=-4} = \frac{480}{48} - \frac{480}{96} = 5; \end{aligned}$$

It is also clear that $R_X(0) = 10 - 5 = 5 \Rightarrow E[X^2] = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_X(\omega) d\omega = R_X(0) = 5$;

(d) For this ideal band-limited noise process, $\frac{1}{2\pi} \int_{-\infty}^{\infty} S_N(\omega) d\omega = 2 = E[N^2]$;

$$\begin{aligned} \text{(e)} \quad R_N(\tau) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} S_N(\omega)e^{j\omega\tau} d\omega = \frac{1}{10\pi} \left[\int_{-20\pi}^{-10\pi} e^{j\omega\tau} d\omega + \int_{10\pi}^{20\pi} e^{j\omega\tau} d\omega \right] \\ &= \frac{1}{10\pi} \left[\frac{e^{-j10\pi\tau} - e^{-j20\pi\tau}}{j\tau} + \frac{e^{j20\pi\tau} - e^{j10\pi\tau}}{j\tau} \right] = \frac{1}{5\pi} \left[\frac{\sin 20\pi\tau}{\tau} - \frac{\sin 10\pi\tau}{\tau} \right] = 2 \left[\frac{\sin 5\pi\tau}{5\pi\tau} \right] * \cos 15\pi\tau. \end{aligned}$$

$$\Rightarrow R_Y(\tau) = a^2 R_X(\tau - q) + R_N(\tau) = 10a^2 e^{-2|\tau-q|} - 5a^2 e^{-4|\tau-q|} + 2 \left[\frac{\sin 5\pi\tau}{5\pi\tau} \right] * \cos 15\pi\tau$$

$$\Rightarrow R_Y(0) = 10a^2 e^{-2q} - 5a^2 e^{-4q} + 2;$$

(f) $R_{XY}(\tau) = E[X(t)Y(t+\tau)] = aE[X(t)X(t+\tau-q)] + E[X(t)N(t+\tau-q)]$

$$= aE[X(t)X(t+\tau-q)] = aR_X(\tau-q) \Rightarrow S_{XY}(\omega) = aS_X(\omega) = \frac{480a}{64+20\omega+\omega^2};$$

(g) Since $R_{XY}(\tau) = aR_X(\tau-q)$ has a peak at $\tau = q \Rightarrow q$ can be estimated by evaluating $R_{XY}(\tau)$ from $X(t)$ and $Y(t)$, then doing peak picking over τ .

Problem 6 (Extra Credit: +20%)

Consider a low pass RC circuit that characterize a linear and time-invariance (LTI) system, with a frequency response: $H(s) = b/(s+b)$ with $b = 1/RC$ representing a positive decaying constant. It can be shown that the impulse response of the LTI system is simply $h(t) = be^{-bt}$, $t \geq 0$, and $h(t) = 0$, $t < 0$. A random signal, $X(t)$, passes through the system will produce a random output, $Y(t)$, computed as the following convolution integral: $Y(t) = \int_0^{\infty} X(t-s)h(s)ds$. In general $X(t)$ is not zero mean.

- (a) If $X(t)$ is a white noise with $S_Y(f) = S_0, -\infty < f < \infty$, show that $R_X(\tau) = S_0\delta(\tau)$;
 (b) Find $E[Y(t)]$ and $E[Y(t)Y(t+\tau)]$, and show that $Y(t)$ is wide-sense stationary;
 (c) If $X(t)$ is non-white with $R_X(\tau) = Ke^{-\beta|\tau|}, \beta > 0$, find $S_Y(\omega)$. Determine the value of K such that $S_Y(0) = S_0$, i.e. same dc value as the above white noise case;
 (d) Given the autocorrelation of $X(t)$ in Part (c), find the autocorrelation of the corresponding system output, $R_Y(\tau) = E[Y(t)Y(t+\tau)]$. Verify that when $\beta \rightarrow \infty$, $R_Y(\tau)$ will converge to the solution in Part (b), an intuitive consequence;
 (e) If $\beta \gg b$, i.e. the input spectrum has a much wider bandwidth than that (constant b) of the low pass LTI system response, show that the above white noise approximation in Part (d) still holds, another important result.

Solution:

$$(a) R_X(\tau) = \lim_{F \rightarrow \infty} \int_{-F}^F S_0 e^{-j2\pi f\tau} df = \lim_{F \rightarrow \infty} 2FS_0 \frac{\sin 2F\tau}{2F\tau} = S_0\delta(\tau);$$

$$(b) E[Y(t)] = \int_0^\infty E[X(t-s)]be^{-bs} ds = E[X(t)] \int_0^\infty be^{-bs} ds = E[X(t)];$$

$$E[Y(t)Y(t+\tau)] = \int_0^\infty \int_0^\infty E[X(t-s)X(t+\tau-u)]b^2 e^{-bs} e^{-bu} ds du \quad [\text{for } \tau \geq 0]$$

$$= \int_0^\infty b^2 e^{-bs} ds \int_0^\infty R_X(\tau-u+s) e^{-bu} du = b^2 S_0 \int_0^\infty e^{-bs} e^{-b(s+\tau)} du = \frac{bS_0}{2} e^{-b\tau}$$

$\Rightarrow Y(t)$ is a wide-sense stationary process;

$$(c) \text{ If } R_X(\tau) = Ke^{-\beta|\tau|} \Rightarrow S_X(\omega) = \frac{2K\beta}{\omega^2 + \beta^2} \Rightarrow S_X(0) = \frac{2K}{\beta} = S_0 \Rightarrow K = \frac{\beta S_0}{2};$$

$$(d) E[Y(t)Y(t+\tau)] = \int_0^\infty b^2 e^{-bs} ds \int_0^\infty R_X(\tau-u+s) e^{-bu} du \quad [\text{For } \tau \geq 0]$$

$$= \frac{b^2 \beta S_0}{2} \left\{ \int_0^\infty e^{-(b+\beta)s} ds * \int_0^{s+\tau} e^{-\beta\tau} e^{-(b-\beta)s} du \right\} \quad [\text{For } \tau \geq 0, u-s-\tau < 0]$$

$$+ \frac{b^2 \beta S_0}{2} \left\{ \int_0^\infty e^{-(b-\beta)s} ds * \int_{s+\tau}^\infty e^{\beta\tau} e^{-(b+\beta)s} du \right\} \quad [\text{For } \tau \geq 0, u-s-\tau \geq 0]$$

$$= \frac{b^2 \beta S_0}{2} \left\{ \frac{e^{-\beta\tau}}{-(b-\beta)} \int_0^\infty e^{-(b+\beta)s} [e^{-(b-\beta)(s+\tau)} - 1] ds + \frac{e^{\beta\tau}}{-(b+\beta)} \int_0^\infty e^{-(b-\beta)s} e^{-(b+\beta)(s+\tau)} ds \right\}$$

$$= \frac{b^2 \beta S_0}{2} * \left\{ \frac{1}{(b-\beta)} \left[-\frac{e^{-b\tau}}{2b} + \frac{e^{-\beta\tau}}{b+\beta} \right] + \frac{1}{(b+\beta)} \frac{e^{-b\tau}}{2b} \right\} = \frac{b^2 \beta S_0}{2(b^2 - \beta^2)} * \left[e^{-\beta\tau} - \frac{\beta e^{-b\tau}}{b} \right]$$

$$\Rightarrow R_Y(\tau) = \frac{b^2 \beta S_0}{2(b^2 - \beta^2)} * \left[e^{-\beta|\tau|} - \frac{\beta e^{-b|\tau|}}{b} \right] \Rightarrow Y(t) \text{ is a wide-sense stationary process;}$$

If $\beta \rightarrow \infty, R_Y(\tau) \rightarrow \frac{bS_0}{2} e^{-b|\tau|} \Rightarrow$ same autocorrelation as the white noise case in Part (b);

$$(e) R_Y(\tau) = \frac{bS_0}{2} e^{-b|\tau|} * \frac{1}{1 - (b^2/\beta^2)} * \left[1 - \frac{b}{\beta} e^{-(\beta-b)|\tau|} \right]$$

If $\beta \gg b, R_X(\tau) \approx \frac{bS_0}{2} e^{-b|\tau|} \Rightarrow$ approximating the white noise case.